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⑪ Publication number : **0 607 695 A1**

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## EUROPEAN PATENT APPLICATION

⑳ Application number : **93310459.8**

㉑ Int. Cl.<sup>5</sup> : **B60C 23/06**

㉒ Date of filing : **23.12.93**

㉓ Priority : **24.12.92 JP 344104/92**  
**28.12.92 JP 347669/92**

㉔ Date of publication of application :  
**27.07.94 Bulletin 94/30**

㉕ Designated Contracting States :  
**DE FR GB IT SE**

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㉙ **Method and device for detecting pneumatic abnormalities of a tyre.**

㉚ A method for detecting pneumatic abnormalities of a tyre comprising the steps of: detecting the angular velocity of each wheel, producing a signal proportional to the angular velocity detected directly measuring the pneumatic pressure of only one tyre producing a signal proportional to the pneumatic pressure and arithmetically processing the signals produced in the proceeding steps. A device to which this method is applied is also disclosed.

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The present invention relates to a method and a device for detecting pneumatic abnormalities of a tyre on a vehicle such as a car or a truck. More particularly, the invention relates to a method and a device capable of reducing cost by the use of the wheel speed pulses in an ABS (Anti-lock Braking System) and of detecting simply and reliably simultaneous abnormality of not less than two wheels at minimum increase of cost by installing a pneumatic pressure detector to a wheel.

Pneumatic pressure of tyres greatly influences the performance of vehicles. More particularly deflation of tyres has a close relation to safety for drivers. Hence, many systems for detecting pneumatic abnormalities of a tyre have been proposed. However, these proposals could not realise both high reliability and low cost so that they have not been widely used. Recently, with the spread of ABS, there has been proposed a system with low cost and high reliability wherein the wheel speed pulses in the ABS are utilised. Although the system is reliable in detecting abnormality of one tyre, it is not reliable to simultaneously detect abnormality of two or more tyres.

In the meanwhile, devices for detecting pneumatic abnormalities are classified into several types according to their detection methods. One type of device directly measures the pneumatic pressure of tyres and the other detects a physical quantity such as the amount of deflection or numbered revolutions both of which change with pneumatic pressure.

The former is more reliable than the latter but the device is complicated and expensive because transmission of signals from a rotating body to a static section is difficult. On the other hand, the latter is simple and cheap but it is less reliable than the former.

Also, in systems for detecting pneumatic abnormalities on the basis of wheel speed, abnormalities of tyres are generally determined by the comparison between the wheel speed pulses of the abnormal pneumatic tyre and those of a normal pneumatic tyre. Accordingly, the pneumatic pressure of at least one tyre must be normal, so that the simultaneous abnormality of all wheels cannot be detected theoretically.

In view of the above state of the art, it is an object of the present invention to provide a method and a device for detecting pneumatic abnormalities of a tyre whose cost is low and which has high reliability and can detect simultaneous abnormalities of all wheels on a vehicle.

According to the present invention, there is provided a method for detecting pneumatic abnormalities of tyre on a vehicle, the method comprising the steps of:

- (a) detecting the angular velocity of each wheel,
- (b) producing signals proportional to the detected angular velocities,
- (c) directly measuring the pneumatic pressure of only one wheel of the vehicle,
- (d) producing a signal proportional to the detected pneumatic pressure, and
- (e) arithmetically processing the signals produced in the steps (b) and (d)

wherein with respect to the directly detected wheel, the step (e) comprises:

operating a device which warns of pneumatic abnormalities of a tyre when a difference between the detected pneumatic pressure and a predetermined normal pneumatic pressure is not less than 0.3 kg/cm<sup>2</sup>; and wherein with respect to the other wheels, when the detected pneumatic pressure is normal, step (e) comprises: obtaining ratios of respective angular velocities of the other wheels to an angular velocity of the directly detected wheel,

comparing the obtained ratios with a ratio in a table of wheel angular velocity ratios under normally inflated conditions on the basis of the angular velocity of the detected wheel in step (c)

comparing the angular velocity of the other wheel and an average value of angular velocities of all the wheels, and

operating a device which warns of pneumatic abnormalities of a tyre when the difference between the compared ratios ranges from 0.05 % to 0.60 % or when the difference between the angular velocity of the other wheel and the average value of angular velocities of all the wheels ranges from 0.05 % to 0.60 %.

Then, according to the method of the present invention, when a pneumatic abnormality of the directly detected wheel is warned, the method further comprises a step (f) of:

obtaining the vehicle speed from a table wherein the relation between pneumatic pressure and angular velocity is shown,

obtaining an angular velocity for the directly detected wheel under normal pneumatic pressure, corresponding to the obtained vehicle speed, and

obtaining ratios of respective angular velocities of the other wheels to this angular velocity so that the deflated tyre can be identified.

The method of the present invention preferably includes a step (g) of directly measuring and monitoring the acceleration of the vehicle in a lateral direction, and a step (h) of invalidating the data of angular velocity of each wheel when the absolute value of the acceleration in the lateral direction exceeds 0.06 g (g: gravity).

Further, the method of the present invention, may include a step (i) of directly measuring and monitoring

the acceleration of a vehicle in a forward or backward direction, and a step (j) of invalidating the data for angular velocity of each wheel when the absolute value of the acceleration in the forward to backward direction exceeds 0.03g.

Moreover, the method of the present invention may include a step (k) of invalidating the data for the angular velocity of each wheel when vehicle a brake pedal is pressed and/or a step (l) of measuring the throttle opening, differentiating the measured value, and monitoring the differentiated value, and a step (m) of invalidating the data for the angular velocity of each wheel when the differentiated value exceeds 100 %sec.

In accordance with the present invention, there is also provided a device for detecting pneumatic abnormalities of a tyre on a vehicle comprising:-

angular velocity detecting means for detecting the angular velocity of each wheel,  
angular velocity signal producing means for producing signals proportional to the detected angular velocities,  
pneumatic pressure detecting means for directly detecting the pressure of only one wheel of the vehicle  
pneumatic pressure signal producing means for producing a signal proportional to the obtained pneumatic pressure;  
arithmetically processing means for arithmetically processing the signals from the angular velocity signal producing means and the pneumatic pressure signal producing means,  
wherein with respect to the directly detected wheel, the arithmetically processing means operates a device which warns of a pneumatic abnormality of tyre when the difference between the detected pneumatic pressure and a predetermined normal pneumatic pressure is not less than 0.3 Kg/cm<sup>2</sup>; and wherein with respect to the other wheels, when the detected pneumatic pressure is normal, the arithmetical processing means, obtains ratios of the respective velocities of the other wheels to the angular velocity of the directly detected wheel,  
compares the obtained ratios with a ratio in a table of wheel angular velocity ratios under the normally inflated condition on the basis of the angular velocity of the directly detected wheel,  
compares the angular velocity of the other wheel and an average value of angular velocities of all the wheels, and  
operates a device which warns of pneumatic abnormality of a tyre when the difference between the compared ratios ranges from 0.05 % to 0.06 % or when the difference between the angular velocity of the other wheel and an average value of angular velocities of all the wheels ranges from 0.05 % to 0.06 %.

The device of the present invention preferably includes an identifying means wherein when pneumatic pressure of the directed detected wheel is abnormal, the means obtains vehicle speed from a table wherein the relation between pneumatic pressure and angular velocity is shown,  
obtains an angular velocity for the directly detected wheel under normal pneumatic pressure, corresponding to the obtained vehicle speed, and  
obtains ratios of respective angular velocities of the other wheels to this angular velocity so that the deflated tyre can be identified.

The device of the present invention preferably includes means for directly measuring and monitoring the acceleration of the vehicle in a lateral direction, and means for invalidating the data for the angular velocity of each wheel when the absolute value of the acceleration in the lateral direction exceeds 0.06 g (g: gravity).

Further, the device of the present invention preferably includes means for directly measuring and monitoring the acceleration of the vehicle in a forward or backward direction, and means for invalidating the data for the angular velocity of each wheel when the absolute value of the acceleration in the forward or backward direction exceeds 0.03 g.

Moreover, the device of the present invention preferably includes means for invalidating the data for the angular velocity of each wheel when a vehicle brake pedal is pressed and/or means for measuring throttle opening, differentiating the measured value, and monitoring the differentiated value, and means for invalidating the data for the angular velocity of each wheel when the differentiated value exceeds 100 % sec.

Thus by the present invention for one of the wheels on a vehicle, deflation is detected by directly measuring the pneumatic pressure thereof, and for the other wheels, deflation is detected by the relative value of angular velocity of each wheel to the angular velocity of the directly detected wheel or an average value of angular velocities of all the wheels.

Described here below is a method for detecting pneumatic abnormalities of tyre on a vehicle according to the present invention (hereinafter referred to as the detection method) in each step.

In step (a) angular velocity of rotation (hereinafter referred to as angular velocity) of each wheel is measured from vehicle speed pulses produced in for ABS by using angular velocity detecting means such as a pulse counter. In the step (b), signals proportional to the angular velocities are produced by using angular velocity signal producing means such as a D/A (Digital & Analogue) converter, and the angular velocity of each wheel

is always monitored.

In step (c), a pneumatic pressure detecting/measuring means such as a pressure transducer or the like is mounted on one of the wheels to obtain directly the pneumatic pressure. In step (d), a signal proportional to the pneumatic pressure is produced continuously by the use of a direct current amplifier or the like.

In step (e), at first the pneumatic pressure of wheel A monitored in step (d), (A is the wheel on which the pneumatic detecting means is mounted) is compared with a predetermined normal value. If the difference between the detected pneumatic pressure and the normal value is equal to or greater than 0.3 kg/cm<sup>2</sup>, a warning device for a pneumatic abnormality is operated. Since the pneumatic pressure of wheel A is directly detected, deflation of any pair of the wheels including wheel A, including deflation of all the wheels may be detected and warned. Table 1 shows the dependency of the angular velocities of the tyre (wheel A) on pneumatic pressure and speed.

Table 1

Pneumatic Pressure	Speed					
	20	40	60	80	100	120
Pneumatic pressure	(Km/h)	(Km/h)	(Km/h)	(Km/h)	(Km/h)	(Km/h)
3.0 (Kg/cm <sup>2</sup> )	8.8680 (rad/sec)	17.7340	26.5994	35.4537	44.2984	53.1033
2.6 (Kg/cm <sup>2</sup> )	8.8737	17.7436	26.6124	35.4675	44.3191	53.1361
2.3 (Kg/cm <sup>2</sup> )	8.8816	17.7595	26.6364	35.4993	44.3544	53.1715
2.0 (Kg/cm <sup>2</sup> )	8.8940	17.7835	26.6692	35.5402	44.4018	53.2213
1.7 (Kg/cm <sup>2</sup> )	8.9093	17.8121	26.7077	35.5889	44.4574	53.2811
1.4 (Kg/cm <sup>2</sup> )	8.9208	17.8351	26.7409	35.6282	44.5026	53.3238
1.0 (Kg/cm)	8.9358	17.8600	26.7765	35.6724	44.5596	53.4004

When deflation of wheel A is not detected, the ratios of the angular velocity of wheel A to the respective angular velocities of the other wheels are obtained. These ratios are compared with the values in a table and the device warns of abnormalities of a tyre when the difference between the compared ratios ranges from 0.05 % to 0.06 %. Further, an average value for the angular velocity of all the wheels detected in step (a) is obtained and compared with the respective angular velocities of the other wheels. The device preferably warns of abnormalities of a tyre when the difference ranges from 0.05 % to 0.6%. Thus deflation of any couple of wheels except wheel A are detected and signalled.

Warning can be performed by using buzzers or the like which appeal to the ears or by using lamps or the like which appeal to the eyes.

In step (e), a table is required wherein the angular velocity pitch is fixed and ratios of angular velocity of each wheel to the normal angular velocity of wheel A at each range of the pitch are shown. Such a table can be prepared by driving on a straight course at each specific speed under normal pneumatic pressure and obtaining ratios for angular velocities at each specific speed. An example of such table is Table II. The pneumatic pressure measuring means was mounted on the front left wheel for Table II.

Table II

	20 (km/h)	40 (km/h)	60 (km/h)	80 (km/h)	100 (km/h)	120 (km/h)
Front left wheel	1.00000	1.00000	1.00000	1.00000	1.00000	1.00000
Front right wheel	1.00151	1.00151	1.00152	1.00152	1.00153	1.00153
Rear left wheel	0.99783	0.99776	0.99767	0.99756	0.99745	0.99732
Rear right wheel	0.99933	0.99927	0.99918	0.99908	0.99898	0.99885

As described above, according to the present invention, deflation of any pair of the wheels, including deflation of all the four wheels, can be detected. Combination deflation is detected by judgement of which wheel(s) is deflated using in combination Table I and Table II. An embodiment is as follows when the pneumatic pressure of wheel A under normal condition is 2.0 Kg/cm<sup>2</sup>.

At first the pneumatic pressure is measured by a pressure transducer and the like, and the measured value is compared with a predetermined normal value so that it is judged whether wheel A is normal or not.

1. When the pneumatic pressure of wheel A is found to be normal, the vehicle speed is obtained from Table I by using the pneumatic pressure of wheel A detected in step (c) and the angular velocity of wheel A detected in step (a). Then, ratio of the angular velocity of each wheel under normal condition at the speed is obtained from Table II.

The angular velocity of each wheel detected in step (a) is divided by the angular velocity of wheel A then, the obtained ratio is compared with the ratio of angular velocity for each wheel under normal condition so that it is judged whether each wheel is normal or not.

2. When the pneumatic pressure of wheel A is abnormal the vehicle speed is obtained from Table I by using the pneumatic pressure of wheel A detected in step (c) and an angular velocity for wheel A detected in step (a). Then, a ratio of the angular velocity of each wheel under normal condition at the speed is obtained in Table II.

An angular velocity is obtained from Table I at the vehicle speed obtained as stated above when the pneumatic pressure of wheel A is normal (2.0 Kg/cm<sup>2</sup>). the angular velocity of each wheel detected in step (a) is divided by this angular velocity for wheel A. Then the obtained ratio is compared with the ratio of the angular velocity of each wheel under the normal condition so that it can be judged whether each wheel is normal or not.

The angular velocity detected in step (a) changes with causes other than deflation of a tyre, such as turning, acceleration or speed reduction and the like, which makes the device warning of abnormality of a tyre operate wrongly. The method and the device for detecting pneumatic abnormalities of a tyre of the present invention, including a method and a device preventing such wrong warnings, is described here below.

In this method the determination of turning and, acceleration or deceleration of a vehicle is performed not by calculating the angular velocity of each tyre, but by directly measuring the accelerations of the vehicle in the lateral direction and in the forward or backward direction, whereby abnormal values can be surely eliminated.

In a step (g), the acceleration of the vehicle in the lateral direction is measured by a lateral acceleration sensor mounted on the vehicle to be monitored with a microcomputer or the like. As a lateral acceleration sen-

sor, for example, a piezo-electric acceleration transducer or a strain gauge acceleration transducer or the like can be used. These sensors can directly measure the acceleration of the vehicle in the lateral direction without using information from any tyre such as the angular velocity of each tyre. Hence, the acceleration in the lateral direction can be measured accurately, independently of the status of the tyres.

On the other hand the angular velocity of each tyre is measured by a rotation pulse generator or the like which is continuously monitored by a microcomputer or the like.

In the step (h), the data for the angular velocity of each wheel is automatically eliminated by using a microcomputer or the like when acceleration in the lateral direction exceeds 0.06 g so that deflation of tyres is only detected by using data which is not eliminated. When the acceleration in the lateral direction exceeds 0.06 g, the obtained data cannot be used because a cause other than deflation of a tyre, such as turning of the vehicle may make differences in angular velocity between the inner wheels and the outer wheels which makes the warning device operate wrongly.

Instead of acceleration in the lateral direction, it is also possible in step (i) to measure the acceleration of the vehicle in the forward or backward directions by a forward-backward acceleration sensor mounted on the vehicle which monitors continuously to a microcomputer or the like. Thus the forward-backward acceleration sensor, for example, a piezo-electric acceleration transducer or a strain gauge acceleration transducer can be used. These sensors can directly measure the acceleration of the vehicle in the forward or backward direction without using information from the tyres such as the angular velocity of a tyre. Hence, the acceleration in the forward or backward direction can be measured accurately, irrelevant of the status of the tyres.

Then, in a step (j), the data for the angular velocity of each wheel is automatically eliminated by using a microcomputer or the like when the acceleration in the forward or backward direction exceeds 0.03 g so that deflation of the tyres is detected by using only data which is not eliminated. When the acceleration in the forward or backward direction exceeds 0.03 g, the obtained data cannot be used because, causes other than deflation of a tyre, such as tyre slip caused by driving or braking make differences in the angular velocities of the tyres.

Further, in a step (k), it is preferable that the data for the angular velocity of each wheel is automatically eliminated by using a microcomputer or the like when the vehicle brake pedal is pressed. When the braking pedal is pressed, the obtained data cannot be used because tyre slip caused by braking makes differences among the angular velocities of the tyres.

Also, as another method, in a step (l), the throttle opening is measured with a sensor such as a throttle sensor. The measured value is differentiated by using a differentiating circuit, a microcomputer or the like and is continuously monitored by a microcomputer or the like. Then, in a step (m), the differentiated value exceeds 100 %/sec; the data for the angular velocity of each tyre is automatically eliminated by using a microcomputer or the like. When the differentiated value exceeds 100 %/sec; the obtained data cannot be used because tyre slip makes differences among the angular velocities of the tyres, which makes the warning device operate wrongly.

As well as the above ways individually, it is possible to combine two or three of the ways, and also to use all the four ways. Thus, the abnormal values can be eliminated more accurately than by using the ways individually.

According to the above ways, the condition for eliminating abnormal values such as vehicle acceleration can be directly obtained without the use of information from the tyres so that abnormal values can be eliminated irrelevant of the status of each tyre.

The detection method of the present invention utilises wheel pulses in the ABS so that the reliability of the method is high and the cost of the method is decreased. Deflation of one of the wheels is directly detected by a pneumatic pressure detecting means, and deflation of the other wheels are detected by using the relative value of angular velocity for each wheel to the angular velocity of the detected wheel or an average value of angular velocities of all the wheels. Consequently, direct detecting means is mounted on only one wheel, which minimises the cost of the device and prevents complications of the device, and the invention can accurately detect and warn deflation of any pair of the wheels including deflation of all the wheels.

Though several embodiments of the present invention are described above, it is to be understood that the present invention is not limited only to the above-mentioned and various changes and modifications may be made in the invention without departing from the spirit and scope thereof.

## Claims

1. A method for detecting pneumatic abnormalities of a tyre on a vehicle, the method characterised by the steps of

- (a) detecting the angular velocity of each wheel
  - (b) producing signals proportional to the detected angular velocities,
  - (c) directly measuring the pneumatic pressure of only one wheel of the vehicle,
  - (d) producing a signal proportional to the detected pneumatic pressure, and
  - 5 (e) arithmetically processing the signals produced in the steps (b) and (d)
- wherein with respect to the directly detected wheel, the step (e) comprises:-  
operating a device which warns of a pneumatic abnormality of a tyre when the difference between the  
detected pneumatic pressure and the predetermined normal pneumatic pressure is not less than 0.3  
Kg/cm<sup>2</sup> and wherein with respect to the other wheels, when the detected pneumatic pressure is normal,  
10 obtaining ratios of the respective angular velocities of the other wheels to the angular velocity of the di-  
rectly detected wheel,  
comparing the ratios obtained with a ratio for a table of wheel angular velocity of the detected wheel in  
step (c),  
comparing the angular velocity of the other wheel and an average value of angular velocities of all the  
15 wheels, and  
operating a device which warns the pneumatic abnormalities of tyre when the difference between the  
compared ratios ranges from 0.05 % to 0.60 % or when the difference between the angular velocity of  
the other wheel and an average value of angular velocities of all the wheels ranges from 0.05 % to 0.06  
%.
- 20 2. The method of Claim 1, characterised in that the method further comprises a step (f) of:  
when a pneumatic abnormality of the directly measured wheel is warned,  
obtaining a vehicle speed from a table wherein the relation between pneumatic pressure and angular ve-  
locity is shown,  
25 obtaining an angular velocity for the directly detected wheel under normal pneumatic pressure, corre-  
sponding to the obtained vehicle speed, and  
obtaining ratios of respective angular velocities of the other wheels to this angular velocity so that the  
deflated tyre can be identified.
- 30 3. The method of Claim 1 characterised in that the method further includes steps of:  
(g) directly measuring and monitoring the acceleration of the vehicle in a lateral direction, and  
(h) invalidating the data for the angular velocity of each wheel when an absolute value of the acceler-  
ation in the lateral direction exceeds 0.06 g.
- 35 4. The method of Claim 1 characterised in that the method further includes the steps of:  
(i) directly measuring and monitoring the acceleration of the vehicle in a forward or backward direction,  
and  
(j) invalidating the data for the angular velocity of each wheel when the absolute value of acceleration  
in the forward or backward direction exceeds 0.03 g.
- 40 5. The method of Claim 2, characterised in that the method further includes a step  
(k) of invalidating the data for the angular velocity of each wheel when the vehicle brake pedal is pressed.
6. The method of any of Claims characterised in that the method further includes the step of:  
(l) measuring the throttle opening, differentiating the measured values, monitoring the differentiated val-  
45 ue, and (m) invalidating the data for the angular velocity of each wheel when the differentiated value ex-  
ceeds 100 %/sec.
7. A device for detecting pneumatic abnormalities of tyre on a vehicle characterised by  
angular velocity detecting means for detecting an angular velocity for each wheel,  
50 angular velocity signal producing means for producing signals proportional to the detected angular ve-  
locities,  
pneumatic pressure measuring means for directly measuring only one wheel of the vehicle,  
pneumatic pressure signal producing means for producing a signal proportional to the measured pneu-  
matic pressure,  
55 arithmetical processing means for arithmetically processing the signals from the angular velocity signal  
producing means and the pneumatic pressure signal producing means  
wherein with respect to the directly detected wheel, the arithmetical processing means  
operates a device which warns of a pneumatic abnormality of a tyre when the difference between the

detected pneumatic pressure and a predetermined normal pneumatic pressure is not less than 0.3 Kg/cm<sup>2</sup>; and;

wherein with respect to the other wheels, when the detected pneumatic pressure is normal, the arithmetical processing means

obtains ratios for the respective angular velocities of the other wheels to an angular velocity of the directly detected wheel,

compares the ratios with a ratio in a table of wheel angular velocity ratio under the normal inflation condition on the basis of the angular velocity of the directly measured wheel,

compares the angular velocity of the other wheel and an average value of angular velocities of all the wheels, and

operates a device which warns of a pneumatic abnormality of tyre when the difference between the compared ratios ranges from 0.05 % to 0.60 % or when the difference between the angular velocity of the other wheel and an average value of angular velocities of all the wheels ranges from 0.05 % to 0.60 %.

8. The device of Claim 7, characterised in that the device further includes an identifying means wherein when pneumatic pressure of the directly detected wheel is abnormal, the means obtains a vehicle speed from a table wherein the relation between pneumatic pressure and angular velocity is shown,

obtains an angular velocity for the directly measured wheel under normal pneumatic pressure, corresponding to the speed, and

obtains ratios of respective angular velocities of the other wheels to this angular velocity so that the deflated tyre can be identified.

9. The device of Claim 7 or 8 characterised in that the device further includes:  
means for directly measuring and monitoring acceleration of the vehicle in a lateral direction, and  
means for invalidating the data for the angular velocity of each wheel when the absolute value of the acceleration in the lateral direction exceeds 0.06 g.

10. The device of Claim 7 or 8 characterised in that the device further includes:  
means for directly measuring and monitoring the acceleration of a vehicle in a forward or backward direction, and  
means for invalidating the data for the angular velocity of each wheel when the absolute value of the acceleration in the forward or backward direction exceeds 0.03 g.

11. The device of any one of Claims 7-10 characterised in that the device further includes;  
means for invalidating the data for the angular velocity of each wheel when a vehicle brake pedal is pressed

12. The device of any one of Claims 7 - 11 characterised in that the device further includes:  
means for measuring the throttle opening, differentiating the measured value, and monitoring the differentiated value and  
means for invalidating the data for the angular velocity of each wheel when the differentiated value exceeds 100 %/sec.





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# EUROPEAN SEARCH REPORT

Application Number  
EP 93 31 0459

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. CL.5)
Y	EP-A-0 083 771 (BMW)  * page 2, line 22 - page 5, line 30; figure *	1-5,7-9, 11	B60C23/06
Y	EP-A-0 291 217 (SP TYRES)  * page 5, line 41 - line 45; figure *	1-3,5, 7-9,11	
Y	FR-A-2 271 063 (MAYER) * page 4, line 33 - line 38; claims 2,3; figure 2 *	4	
			TECHNICAL FIELDS SEARCHED (Int. CL.5)
			B60C
The present search report has been drawn up for all claims			
Place of search THE HAGUE		Date of completion of the search 25 March 1994	Examiner Hageman, L
CATEGORY OF CITED DOCUMENTS		T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons A : member of the same patent family, corresponding document X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document	

EPO FORM 150 (3.9.93) (EN/CN)